

UNITED STATES AIR FORCE RESEARCH LABORATORY

MAXPAC Test Program Final Presentation

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Final Report for the Period July 1996 to December 1996

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Human Effectiveness Directorate Biodynamics and Protection Divison Biodynamics and Acceleration Branch 2800 Q Street BLDG 824 RM 206 Wright-Patterson AFB OH 45433-7947

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AFRL-HE-WP-SR-2001-0006

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This technical report has been reviewed and is approved for publication.

FOR THE DIRECTOR

F. WESLEY BAUMGARDNER

Acting Chief, Biodynamics and Protection Division

Human Effectiveness Directorate

Air Force Research Laboratory

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PREFACE

This report was prepared under contract F41624-95-C-6014, Task 62, Engineering Support of Biodynamics Research – Crew Escape Technologies (CREST) Demonstration Support. The Prime Contractor for this effort was Veridian Engineering, Inc., Dayton, OH and the major subcontractor was Aerojet – Propulsion Division of Sacramento CA.

This Final Report summarizes the results of a United States Air Force funded effort during the period July through December 1996 to demonstrate the Multi-Axis Pintle Attitude Control (MAXPAC) system. The MAXPAC system is a spin-off of the Fourth Generation Escape System Technology Demonstration program. The intent of the program was to provide an under-seat retrofit for the Advanced Concept Ejection Seat (ACES) II replacing the current pitch stabilization rocket with the three-axis stabilization MAXPAC.

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***96 MAXPAC MOTOR TEST PROGRAM** FINAL PRESENTATION



AGENDA

- → MAXPAC OVERVIEW
- PROGRAM OBJECTIVES AND STATUS
- REVIEW OF TEST ARTICLE DESIGN
- KISTLER LOAD TABLE DESCRIPTION
- PROOF TEST RESULTS
- TEST DATA REVIEW AND GROUND TEST GROUNDING ISSUES
- **CONCLUSIONS & RECOMMENDATIONS**





MAXPAC OVERVIEW

JOE MORRIS

(SENCORP AEROJET

MAXPAC MOTOR TEST PROGRAM OBJECTIVES



OBJECTIVE	STATUS
DESIGN & ANALYSIS	CMPLT
MOTOR ASSEMBLY AND BENCH TESTING	CMPLT
TEST PLANS	CMPLT
GROUND STATIC MOTOR TESTS	CMPLT
REPORTING: MONTHLY TECHNICAL & BUDGET, MOTOR TEST QUICKLOOK	CMPLT
MEETINGS: KICK-OFF, TRR, AND FINAL PRESENTATION	66% CMPT



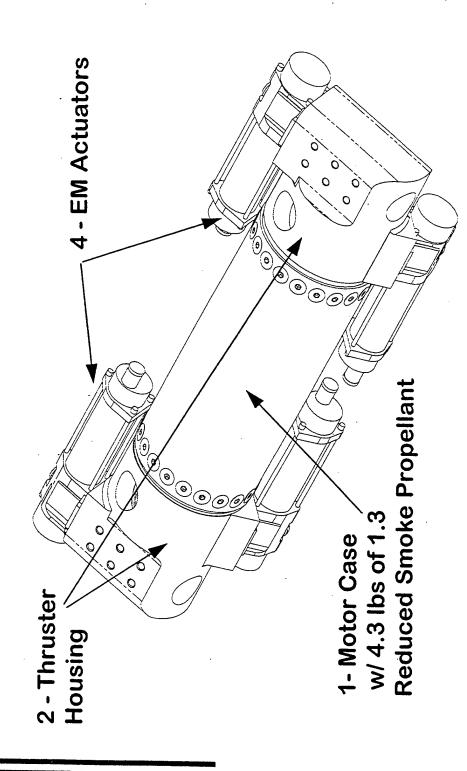


MAXPAC TEST ARTICLE DESIGN REVIEW

BILL BARNETTE

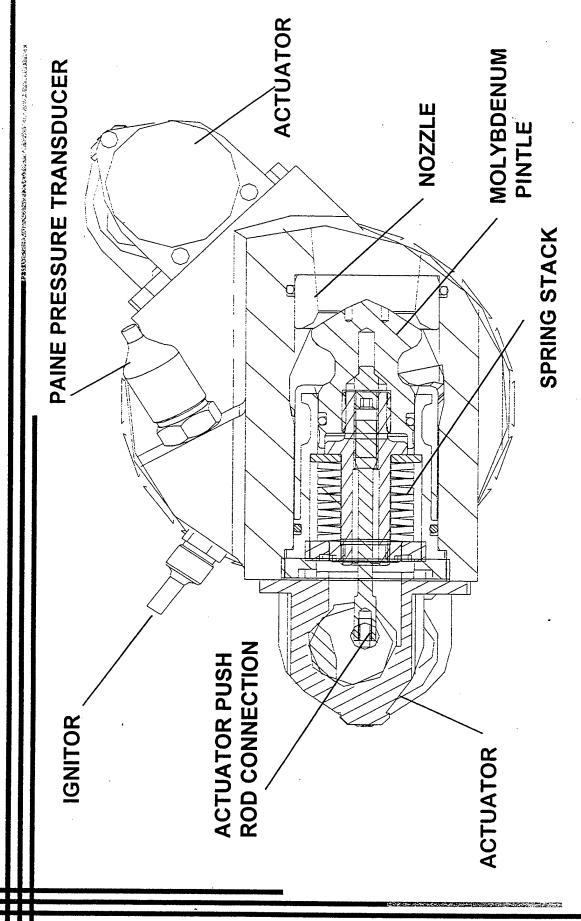


HEAVYWEIGHT MOTOR CONFIGURATION



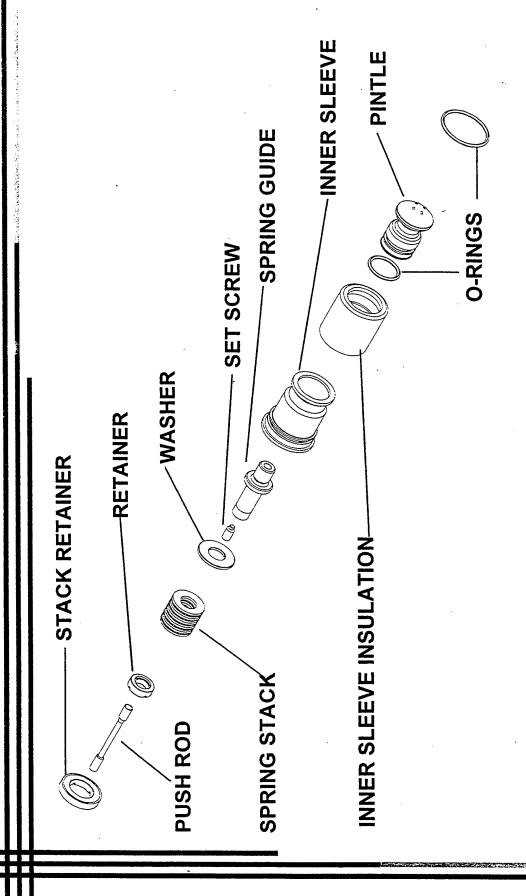
MAXPAC PINTLE MODULE ASSEMBLY





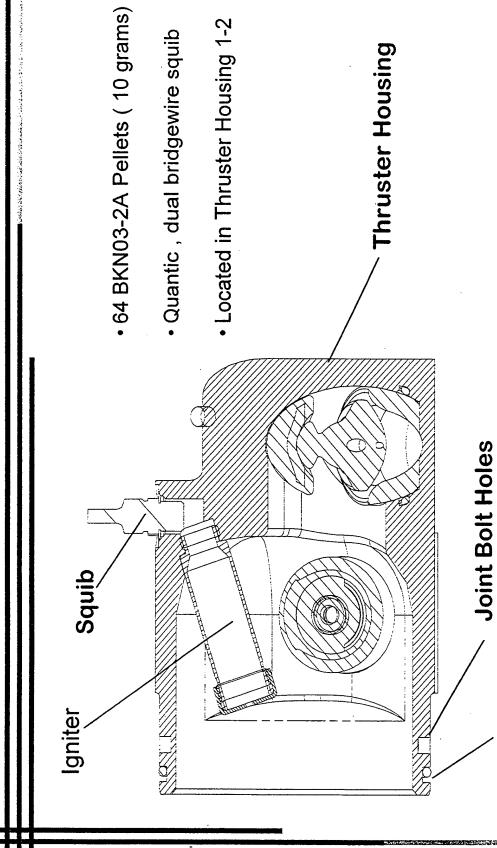
MAXPAC PINTLE MODULE





MAXPAC IGNITER

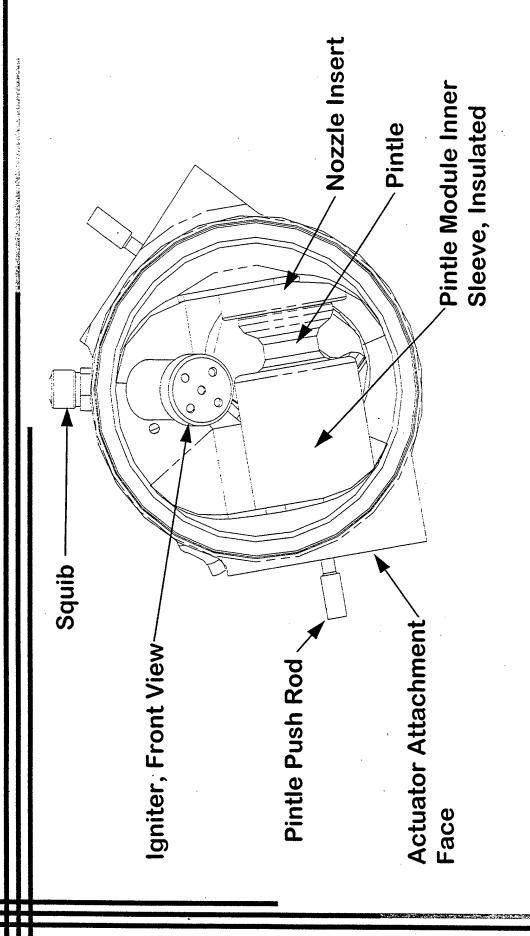




O-ring Groove

THRUSTER HOUSING, INSIDE VIEW

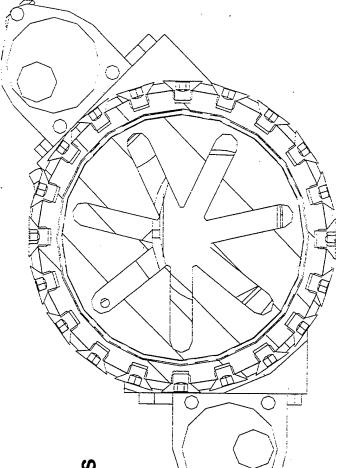




MAXPAC PROPELLANT



- 4.3 Pounds of Modified
 ANB-3679, Developed on
 - the ARS Program Reduced Smoke, Hazards
 - Class 1.3
- 7- Fin Grain Design, Full Length
 - Elastomer Liner for Propellant to Case Bonding
- →9.0 inches Long, ~ 3.8"
 OD, ~0.8" ID, ~ 0.3" Fin
 Gap

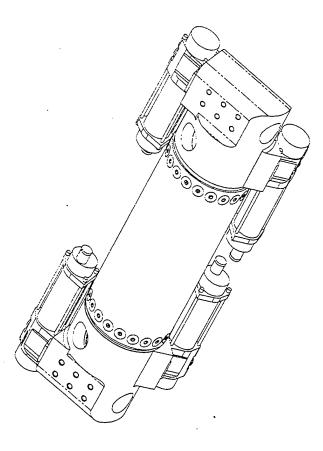


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MAJOR COMPONENTS



- 4- Electro-Mechanical Actuators
 - 150 VDC, 40 Amp
- Stall Load >300 Lbf
- Stroke > 0.22", > 120 HzQuad Actuator Controller Pressure Transducers, PN - 5K Flightweight Paine 77398
- 5K Taber Pressure
- ransducers, Facility Equipment Kistler Load Measuring Table
 - **Motor Hold Down Brackets**







CONTROLS

- Control Logic in "C"
- **EDACS (Engineering Data Acquisition and Control)**
- Pentium 90MHz
- National Instruments Data Acquisition Boards
- **Ectron Strain Gage Amplifiers**
- Validyne Amplifiers
- » Ordnance Firing Circuit
- Sample Rate of 400 Samples / Second
- Backup Data on Separate PC486/50

CONTROL LOGIC



- **MAXPAC Control Logic Identical to 4TH GEN Initial Testing Logic**
- **Iwo Paine Amplified Pressure Transducers for Control**
- **Transducer Logic Checks for Bad Transducer**
- **Thrust Commands Limited to Available System Thrust**
- Initial Pintle Positions at Spring 0-Load Point
- **Versatron Actuators**
- % 120 Hz Bandwidth
- 15 Inches / Second
- 360 lbf
- » 140 VDC @ 40 amps



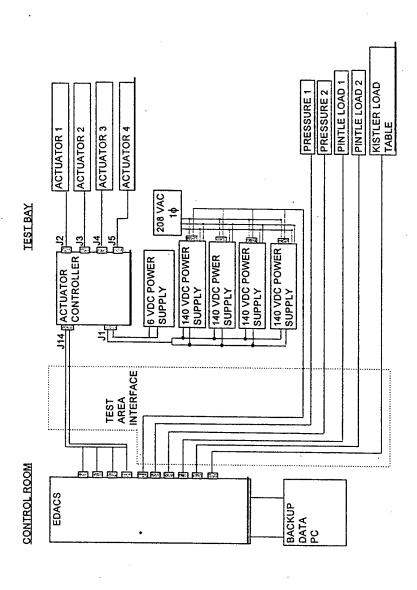
CONTROL LOGIC



- MAXPAC Control Logic Identical to 4TH GEN Initial Testing Logic
- **Two Paine Amplified Pressure Transducers for Control**
- **Fransducer Logic Checks for Bad Transducer**
- **Thrust Commands Limited to Available System Thrust**
- Initial Pintle Positions at Spring 0-Load Point
- Versatron Actuators
- » 120 Hz Bandwidth
- 15 Inches / Second
- 360 lbf
- » 140 VDC @ 40 amps

MAXPAC GROUND TESTING ELECTRICAL INTERFACE





MAXPAC INSTRUMENTATION LIST

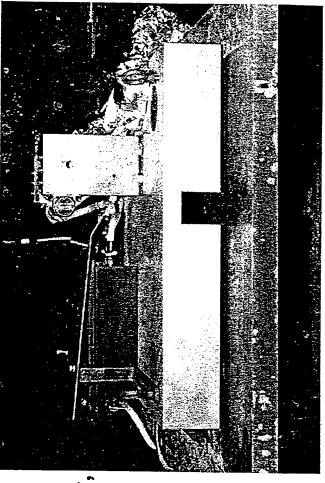


Function	Name	Range	Notes
Chamber Pressure	PC-182	0 - 5,000 psia	2Paines-2Tbrs
Igniter Circuit Current	1-1	TBD amps	
Pintle Actuators (1-4) Current	IAP-1 thru IAP-4	0 -40 amps	
Pintle Actuators (1-4) Voltage	EAP-1 thru EAP-4	0 - 1400 volts	٠
Pintle #1 Actuator Command	CAP-1 thru CAP-4	0 - 10 volts	
Pintle Position	PP-1 thru PP-4	0 - 0.25 inch	
Forces along X, Y Axes	FX, FY	± 4496 lbf	Tests 2 & 3
Forces along Z Axis	FZ .	-4496 to 8993 lbf	Tests 2 & 3
Moments about X, Y Axes	MX, MY	+ 369 ft-lbs	Tests 2 & 3
Moments about Z Axis	MZ	± 738 ft-lbs	Tests 2 & 3
		•	æ

KISTLER LOAD

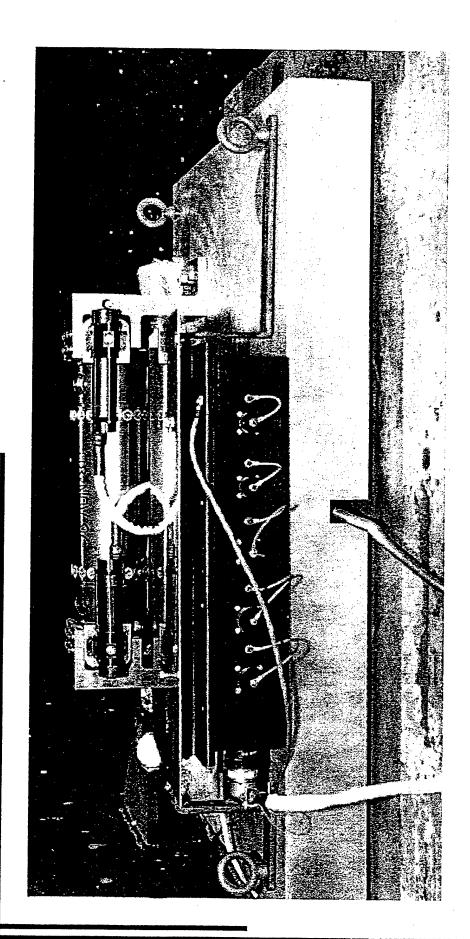


- Multi-component Force Plate Provides 3 Orthogonal Components Of Force, Fx, Fy, & Fz
- Fx&y = \pm 4496 lbf; Fz=-4496 to 8993 lbf
- High Frequency due to Stiffness
- 4 3 axis Quartz Type Load Cells
- Micro-Processor/ Amplifier, Determines Moments and Resultant Forces



KISTLER LOAD TABLE REAR VIEW





PROOF TEST CRITERIA & RESULTS



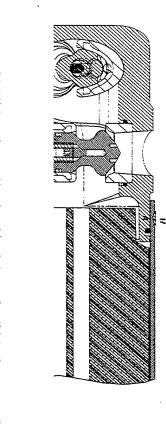
Hydro-Proof Test

20- 1/4" x 28 screws

1/8 Long

Motor Assembled as Planned with Nozzle Plugs Max Pressure 4600 psiMotor Held Target

Pressure for 60 Seconds Joint Failed- Bolts Pulled from Bolt Hole: Bolt L/D was to Small, < 0.7 Critical Ratio



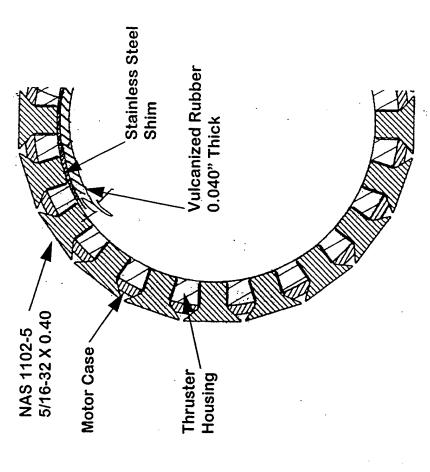


MOTOR CASE JOINT NEAR TERM FIX



encelor recognization of the contradiction of the c

- Brainstorming Session Lead to Near Term Fix
- Salvage Existing Hardware
 - Must Use Larger Bolts
- Drill Through Thruster
 Housing To Acquire More
 Length
- Bond in Stainless Steel Shim
 - Coat Shim Joint with vulcanized rubber
- Consequently Increased L/D
- Long Term Fix, Redesigned Joint, Probably Lockwire





GROUND TEST GROUNDING ISSUES MAXPAC TEST DATA REVIEW AND

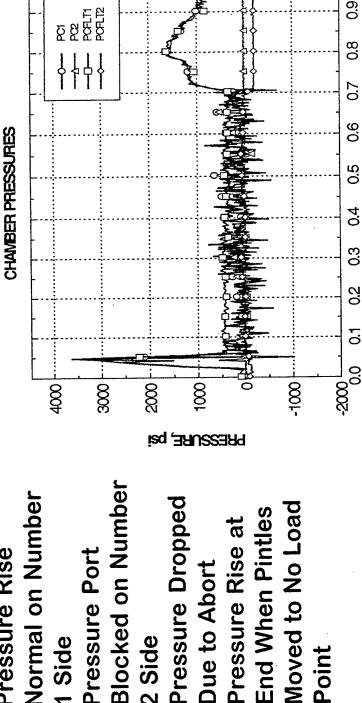
KEVIN PETERSON

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MAXPAC TEST 100 RESULTS



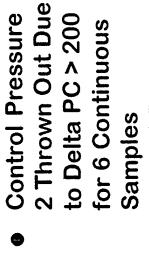
- Normal on Number Pressure Rise
- **Blocked on Number Pressure Port** Side 2 Side
 - **Pressure Dropped End When Pintles** Pressure Rise at **Due to Abort**

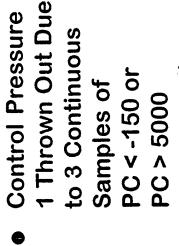


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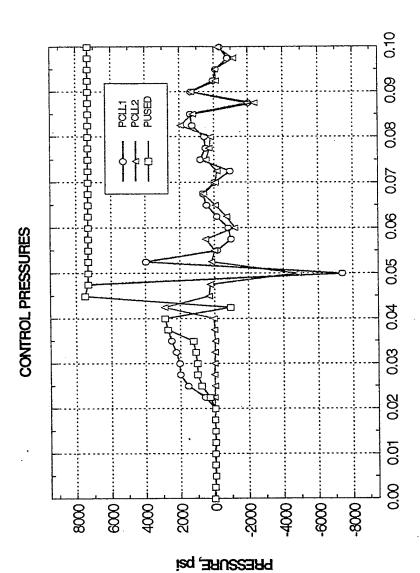
MAXPAC TEST 100 RESULTS







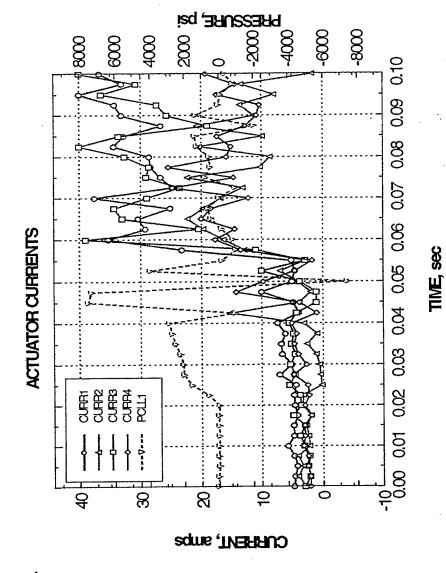




MAXPAC TEST 100 RESULTS



Pressure Transducer
1 Failure Caused by
Noise
Noise Occurred
When Actuator
Current Increased





MAXPAC NOISE ISSUES



- Noise on Pressure Transducer Feedback Signals
- Both The Facility Tabers And The Paine Flight Transducers
- Noise Appeared When Actuators Energized
- Noise Increased With Increased Actuator Current Draw
- Noise Caused Abort on Test 100



Noise Elimination Solutions



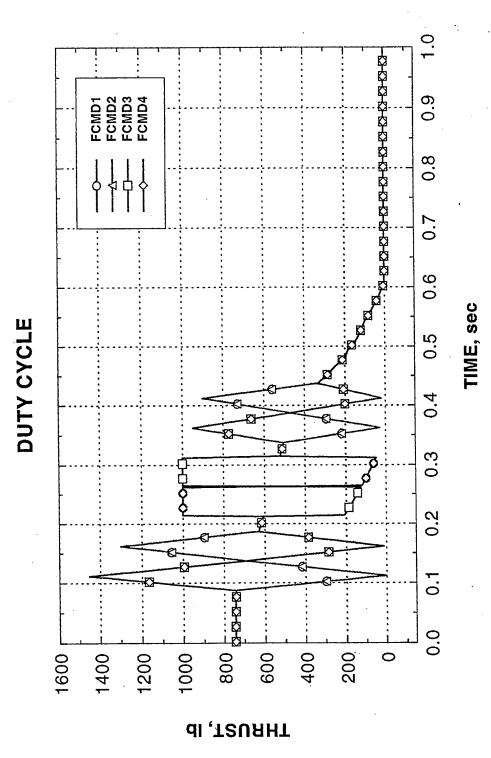
- Versatron Suggested Batteries for Actuator Power
- Noise Significantly Reduced, But Not Eliminated
- Next Step, Grounding
- Common Ground Between Actuator Controller and D/A Card
- Common Ground Between Signal Conditioners
- Tied Actuator Controller Case to Earth Ground
- Tied All Shields to Instrumentation Ground
- Noise Reduced to Acceptable Level on Taber Transducers

(± 10 psi)



MAXPAC TEST 200 RESULTS

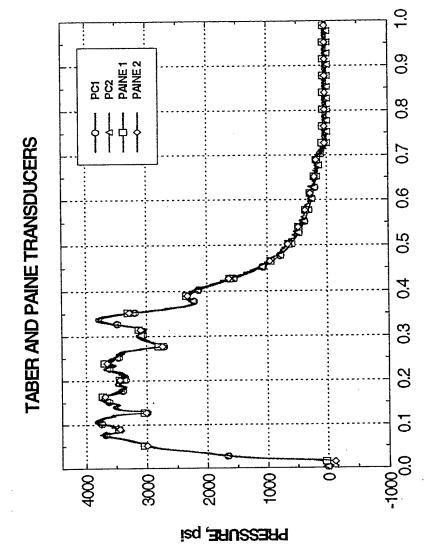




MAXPAC TEST 200 RESULTS



- Noise Effectively
- Eliminated
 Paine Flightweight
 Transducers
 Matched Facility
 Tabers
- Pressure Variations of 500 psi
 - Burn Time Approximately 0.1 sec < Predicted
- Possibly BurnRate Variation

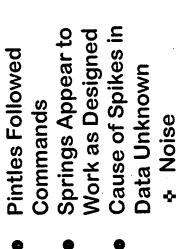


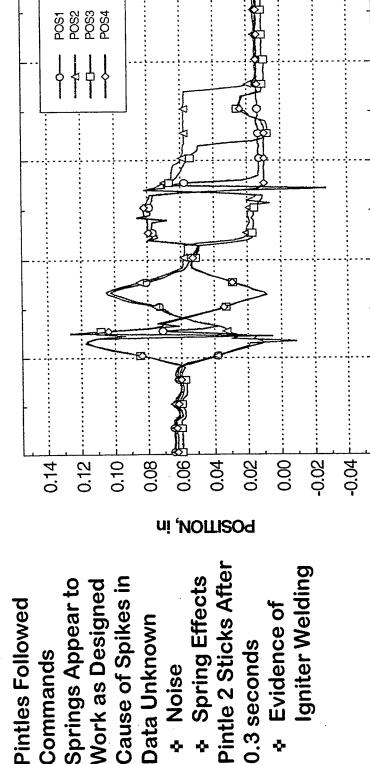
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MAXPAC TEST 200 RESULTS









0.5

0.4

0.3

0.1

TIME, sec

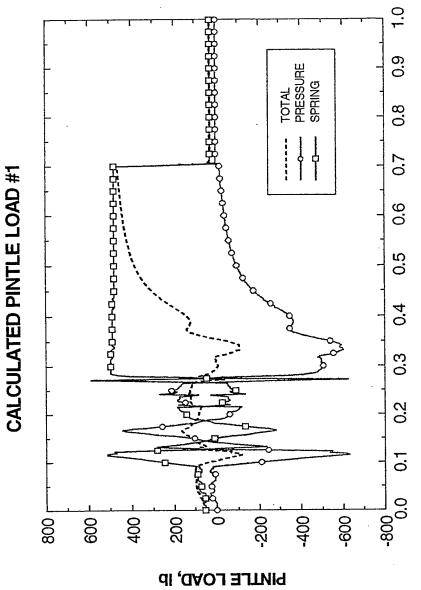
0.3 seconds

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MAXPAC TEST 200 RESULTS



Theoretical Pintle
Loads Kept Below
200 lbs



TIME, sec

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MAXPAC TEST DATA



Kistler Load Table

A Multicomponent Force Plate

Consists of Four Tri-Axis Load Cells

Separate Multichannel Charge Amplifier

Outputs the Following Measurements Fx1+2

X-Axis Load Cell 1 & 2

X-Axis Load Cell 3 & 4 Y-Axis Load Cell 1 & 4

Y-Axis Load Cell 2 & 3

Z-Axis Load Cell 2 Z-Axis Load Cell 1

Z-Axis Load Cell 3 Z-Axis Load Cell 4

Fz4

1/2 X-Axis Thrust

1/2 Z-Axis Thrust 1/2 Y-Axis Thrust 1/2 Fy

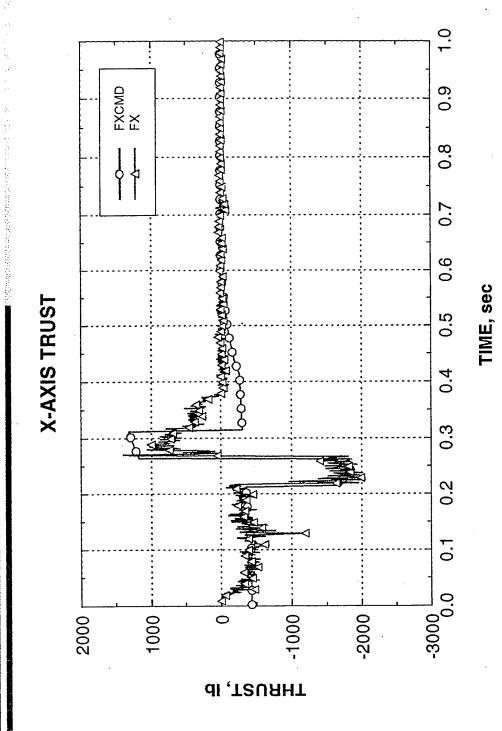
1/4 Moment About X-Axis 1/4 Mx 1/4 Fz

1/4 Moment About Y-Axis 1/4 Moment About Z-Axis 1/4 My

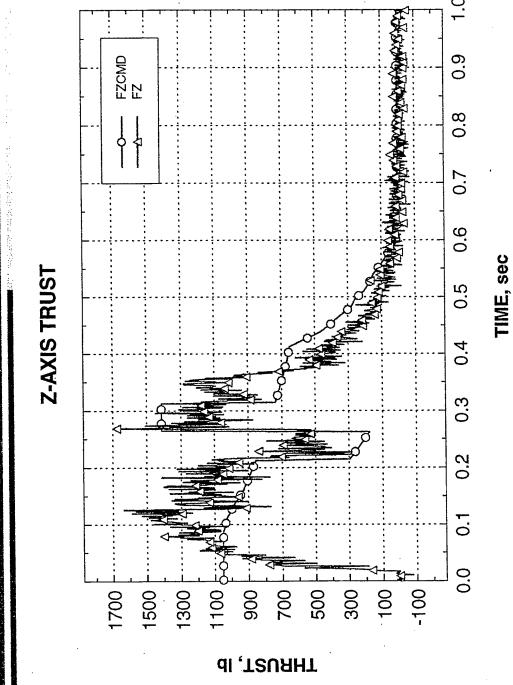
Fx3+4

Fy1+4







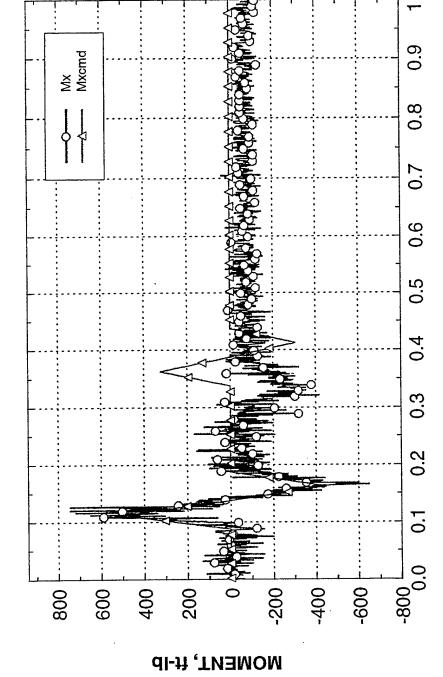


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MAXPAC TEST 200 RESULTS



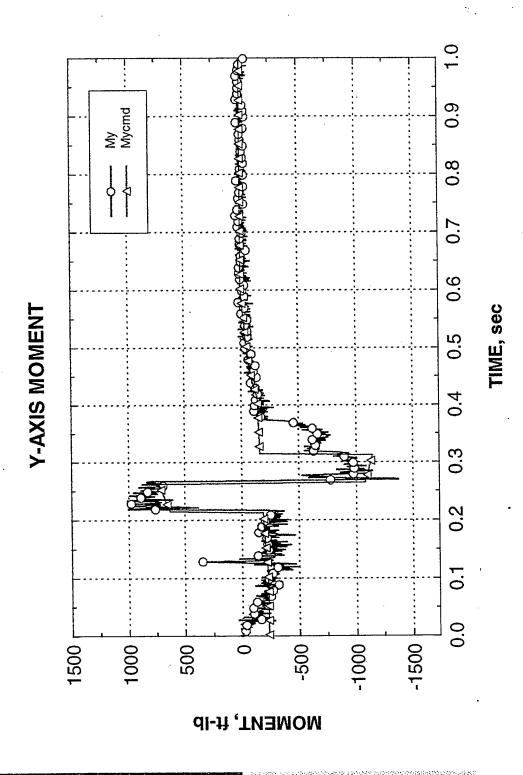




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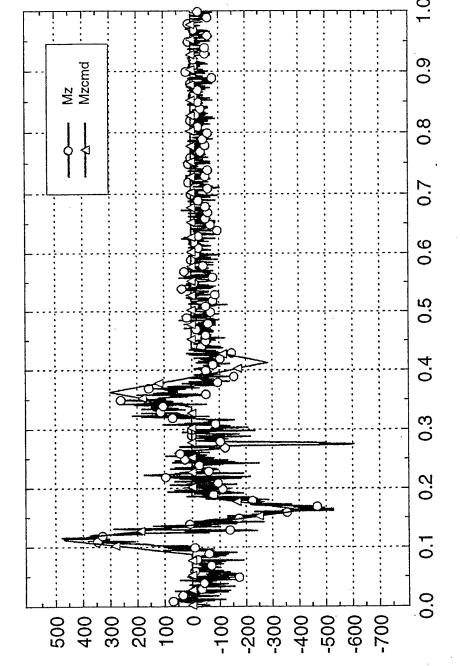










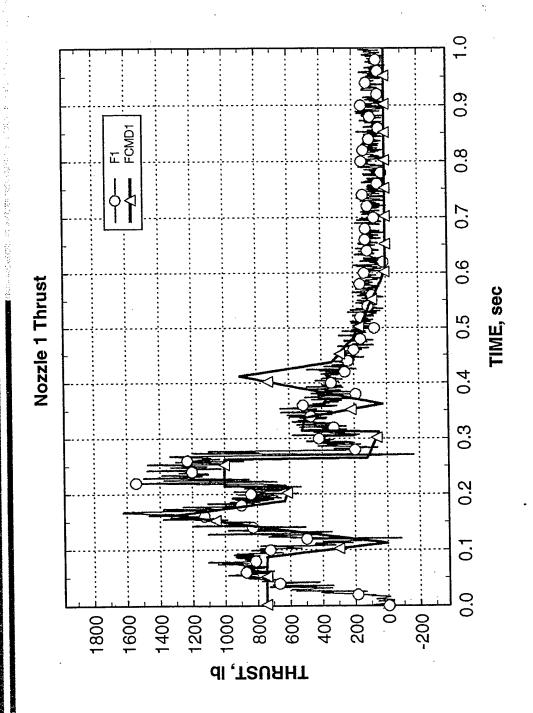


TIME, sec

MOMENT, ft-lb



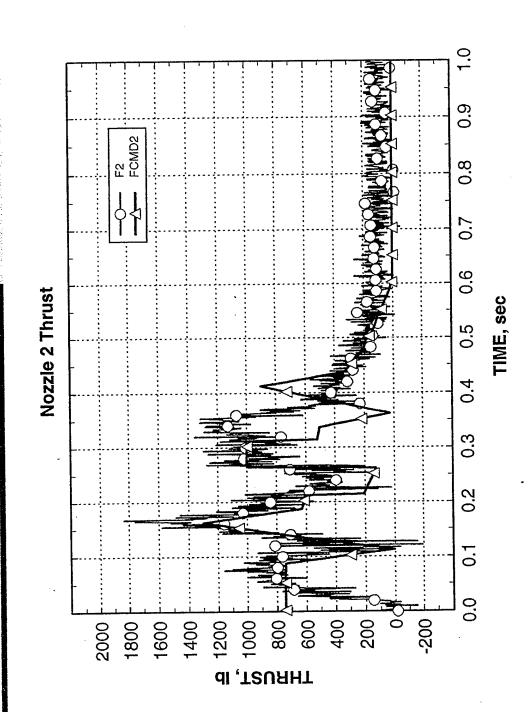






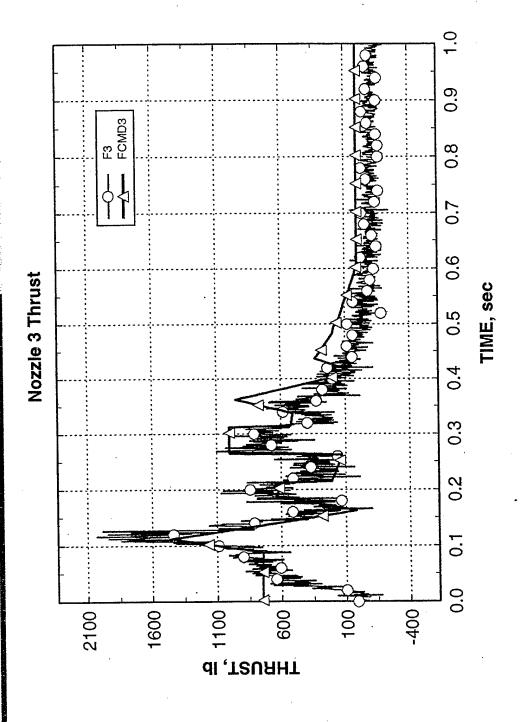
MAXPAC TEST 200 RESULTS





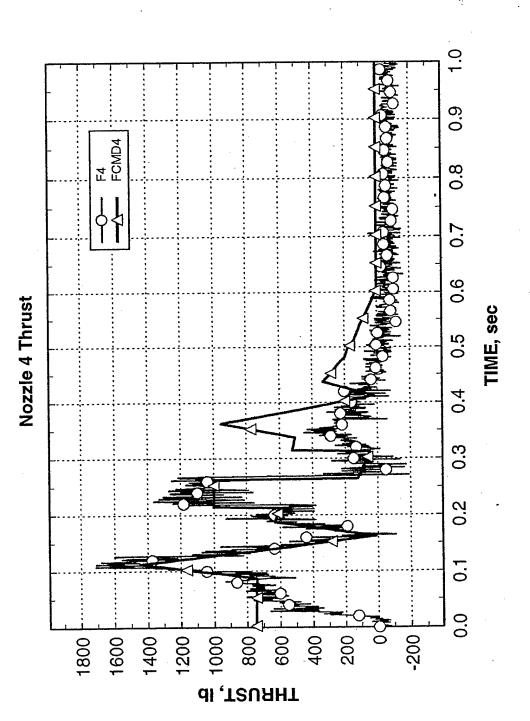








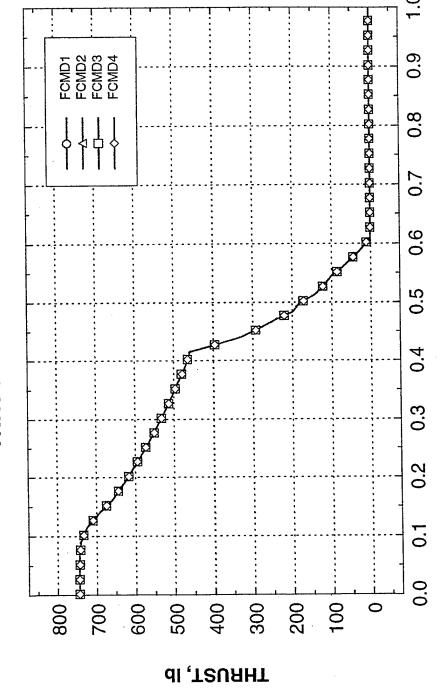












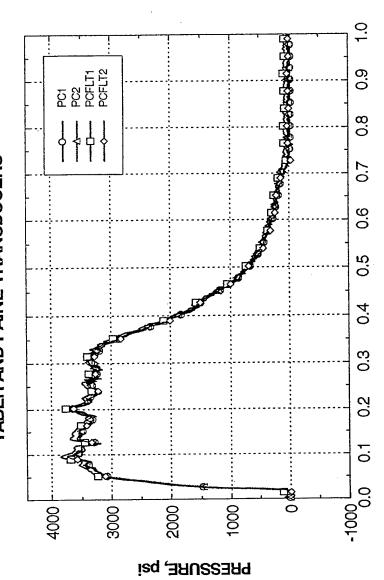
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MAXPAC TEST 300 RESULTS



TABER AND PAINE TRANSDUCERS

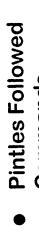
- Paine Flightweight
 Transducers Matched
 Facility Tabers
- Pressure Variations of 300 psi
- Burn Time
 Approximately 0.1 sec
 < Predicted
 + Possibly Burn
 Rate Variation



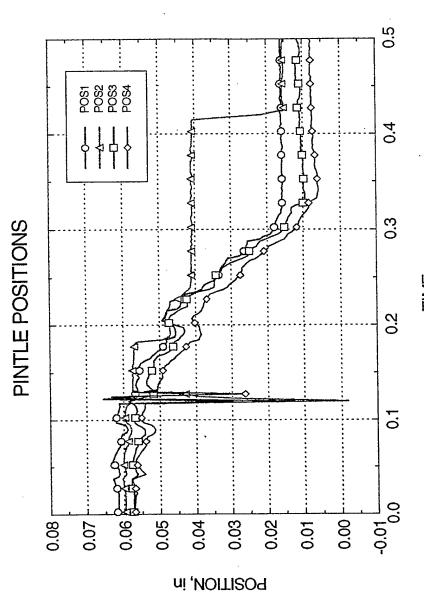
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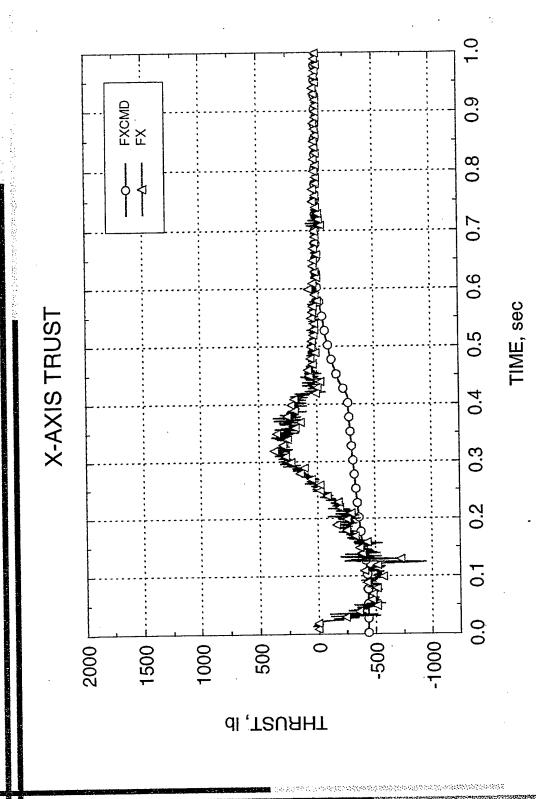




- Springs Appear to Work as Designed Same Type of Spikes Occurred Commands
- NoiseSpring EffectsPintle 2 SticksAgain
 - Igniter Welding ♣ Evidence of

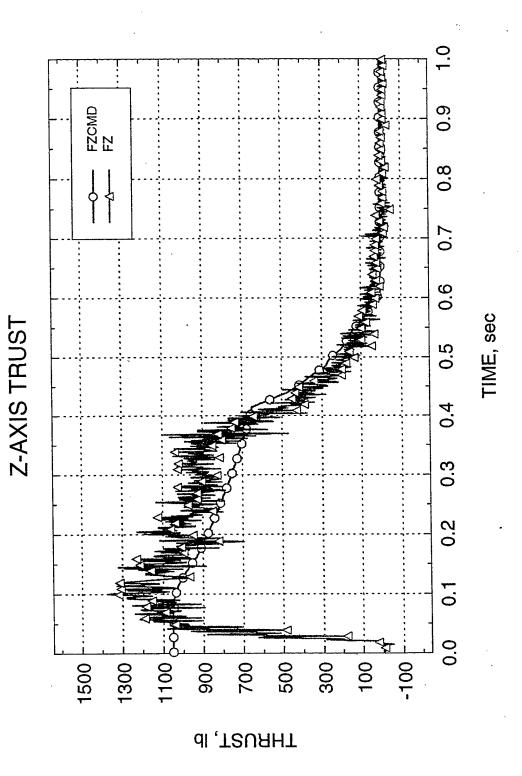






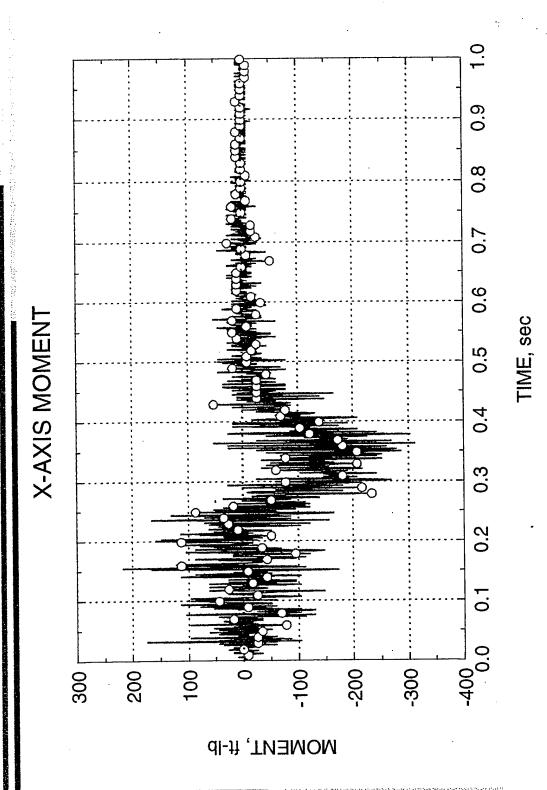






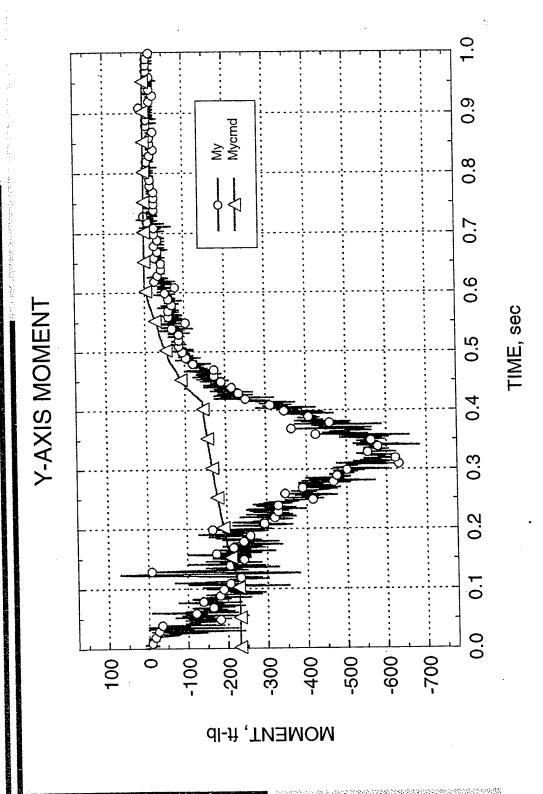






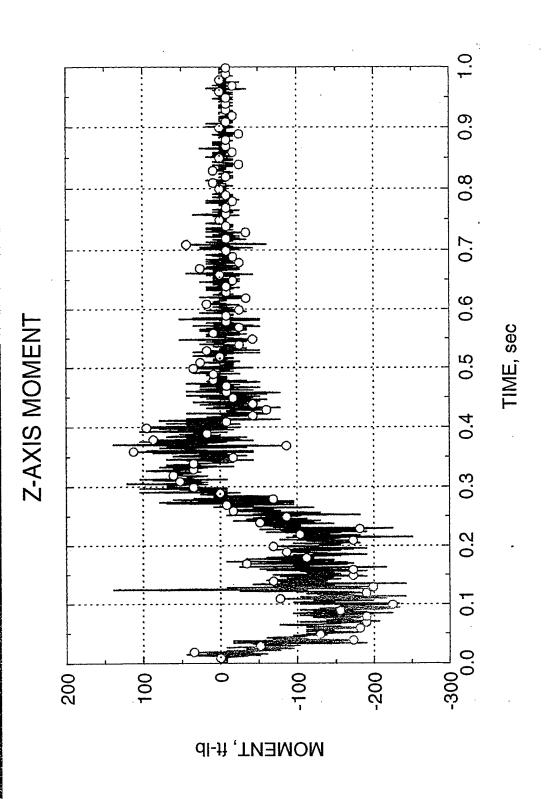






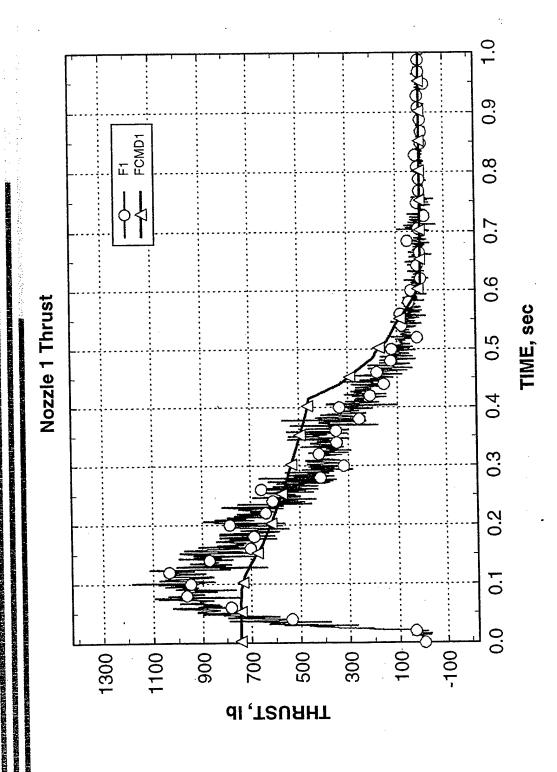






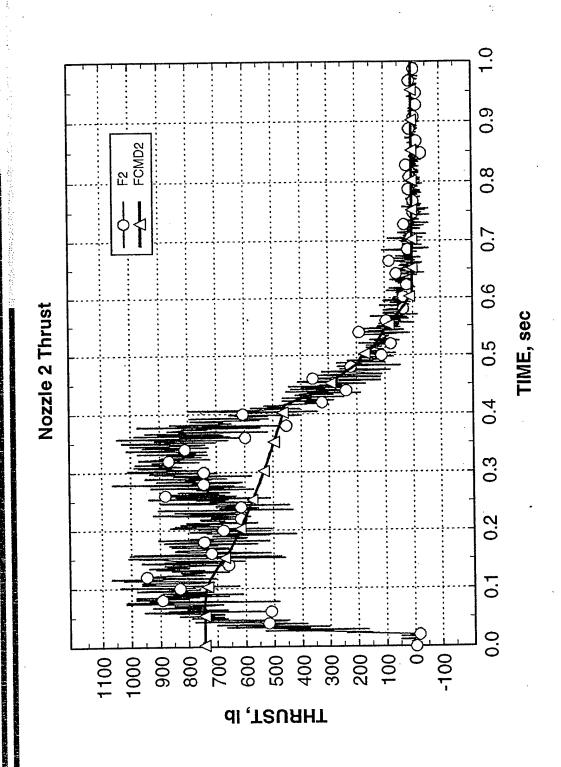






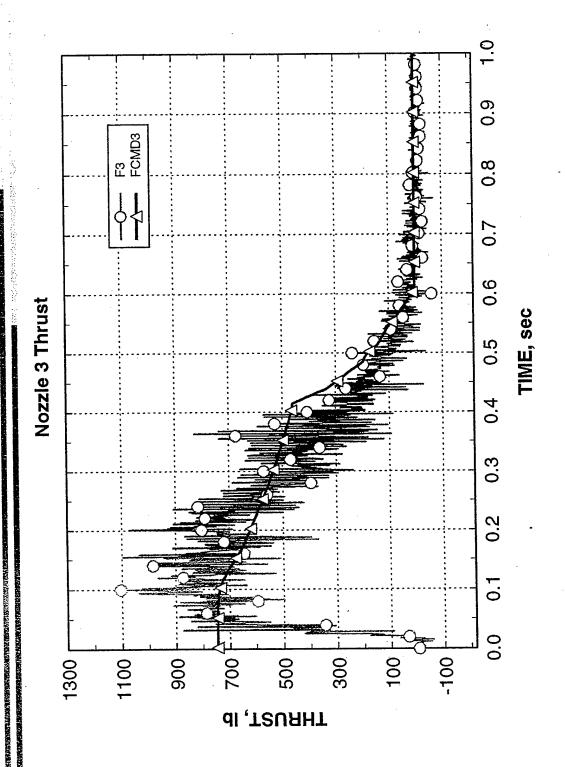
MAXPAC TEST 300 RESULTS





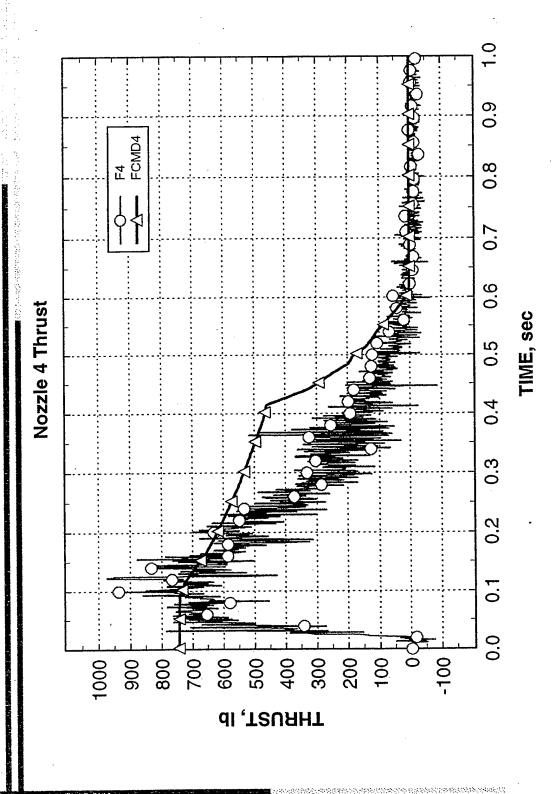






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CONCLUSIONS & RECOMMENDATIONS



CONCLUSIONS

- ALL PROGRAM OBJECTIVES WERE ACHIEVED
- SOME HARDWARE MODIFICATIONS WERE NECESSARY TO **ACCOMPLISH MOTOR TESTING**
 - NEAR TERM CASE JOINT FIX WORKED AS PLANNED
- KISTLER FORCE MEASURING TABLE PERFORMED AS DESIRED
- FEST 2 & 3 PROVIDED CRITICAL DATA ILLUSTRATING THAT THE MAXPAC ROCKET MOTOR DOES PROVIDE THE THRUST LEVELS AND RESPONSE TIMES NECESSARY

RECOMMENDATIONS

- REDESIGN CASE JOINT AND HYDROTEST
- RE: WEIGHT CONDUCT COMPONENT MATERIAL SWAPOUT TESTS REDUCTION
 - CONDUCT 4 OR 5 GROUND TESTS DEMONSTRATING SYSTEM INTEGRATION, (ROCKET MOTOR, EPAC AND SEAT)
 - PREPARE FOR SLED TESTING IN SUMMER OF '97